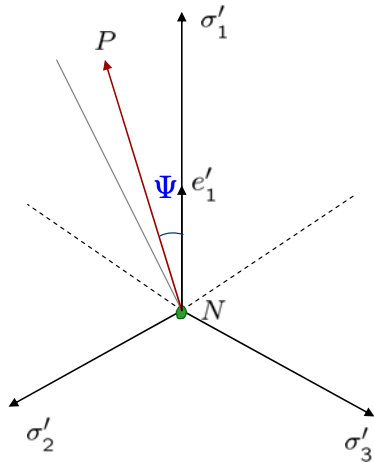
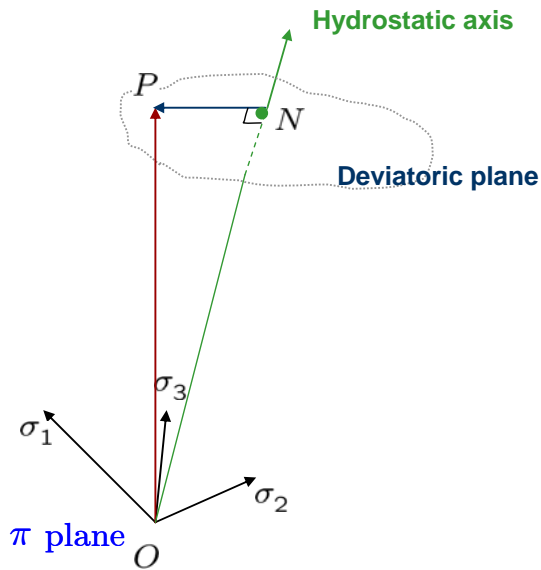
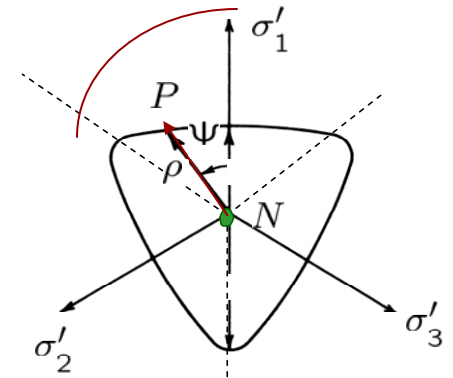


## Constitutive models: Failure Surface



$$f(\sqrt{3}p, \rho, \Psi), \quad \rho = \sqrt{2J_2}$$

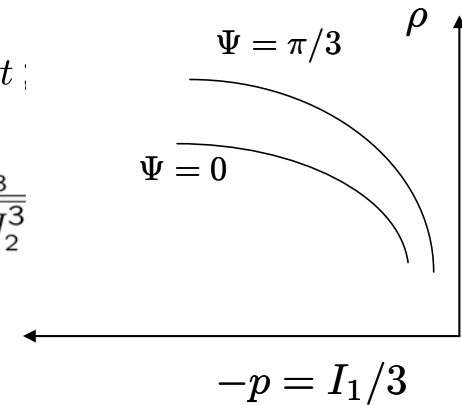
$$p = \text{const}$$



$$f(\sqrt{3}p, \rho, \Psi), \quad \rho = \sqrt{2J_2}$$

$$\Psi = \text{const}$$

$$\cos 3\Psi = \frac{3\sqrt{3}}{2} \frac{J_3}{\sqrt{J_2^3}}$$



## Constitutive models: Failure Surface

$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2}$$

$$\Psi = \text{const}; \quad \Psi = 0, \Psi = \pi/3 \quad \text{meridian plane}$$

### Compressive meridian:

$$\sigma_1 = \sigma_2 > \sigma_3$$

↓

$$\Psi = \pi/3$$

triaxial compression:  
hydrostatic pressure  
+ axial compression

### Tensile meridian:

$$\sigma_3 = \sigma_2 < \sigma_1$$

↓

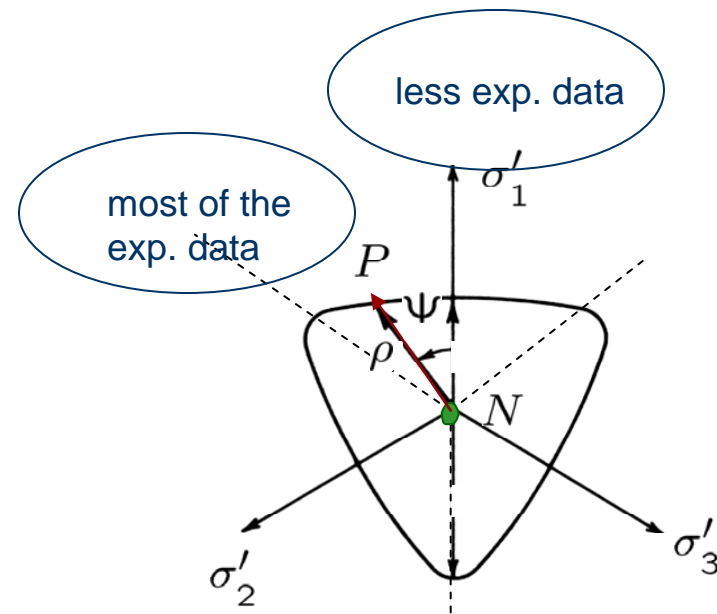
$$\Psi = 0$$

triaxial tension:  
hydrostatic pressure  
+ axial tension

### Shear meridian:

$$\sigma_1, \frac{\sigma_1 + \sigma_3}{2}, \sigma_3$$

$$\Psi = \pi/6$$



## Constitutive models: Failure Models

---

$$f(\sigma_{ij}) = 0$$

### Historical overview

**Hypothesis 1:** the theory of maximum normal stress states: the material strength is completely determined by the stress and the two strength limits in tension,  $\sigma_t$  and compression,  $\sigma_c$ .

Galilei, Leibniz (17c)

$$\begin{aligned}\sigma_3 &= -\sigma_c & \sigma_1 &\leq \sigma_t \\ \sigma_3 &\geq -\sigma_c & \sigma_1 &= \sigma_t\end{aligned}$$

Bauschinger experiments 1874 on steel with different carbon content -> the limit of elastic response in torsion is approx. the half of the elastic limit in tension

**Hypothesis 2:** theory of maximum linear relative deformation (assess material strength through max tensile elongation ( $te$ ))

$$\sigma_1 - k(\sigma_2 + \sigma_3) \leq \sigma_{te}$$

$$\sigma_3 - k(\sigma_1 + \sigma_2) \geq -\sigma_c$$

coefficient of lateral  
compression deformation:

$$k = 1/4$$

⇒ strength in pure compression exceeds 4 times the strength in tension

## Constitutive models: Failure Models

---

$$f(\sigma_{ij}) = 0$$

### Historical overview

#### Hypothesis 3:

the theory of maximum difference in normal stress in which the material strength is defined by the maximum shear stress;  
- only maximum and minimum principal stresses play a role in this theory.

#### Coulomb 1773

$$\tau_{max} = \frac{1}{2}(\sigma_1 - \sigma_3) \leq \frac{\sigma_{te}}{2}$$

Pure shear:

$$\tau_{max} = \sigma_1 = -\sigma_3 \leq \frac{\sigma_{te}}{2}$$

(confirmed by the Bauschinger experiment)

#### Duguet 1882

assumed like Coulomb that the failure is due to shear;  
- resistance to shear failure depends on cohesion and internal friction. The later value changes with change of the normal stress,  $\sigma_\nu$ , acting on the shear plane.

$$\tau + f \sigma_\nu = const$$

$$f = 0.176$$

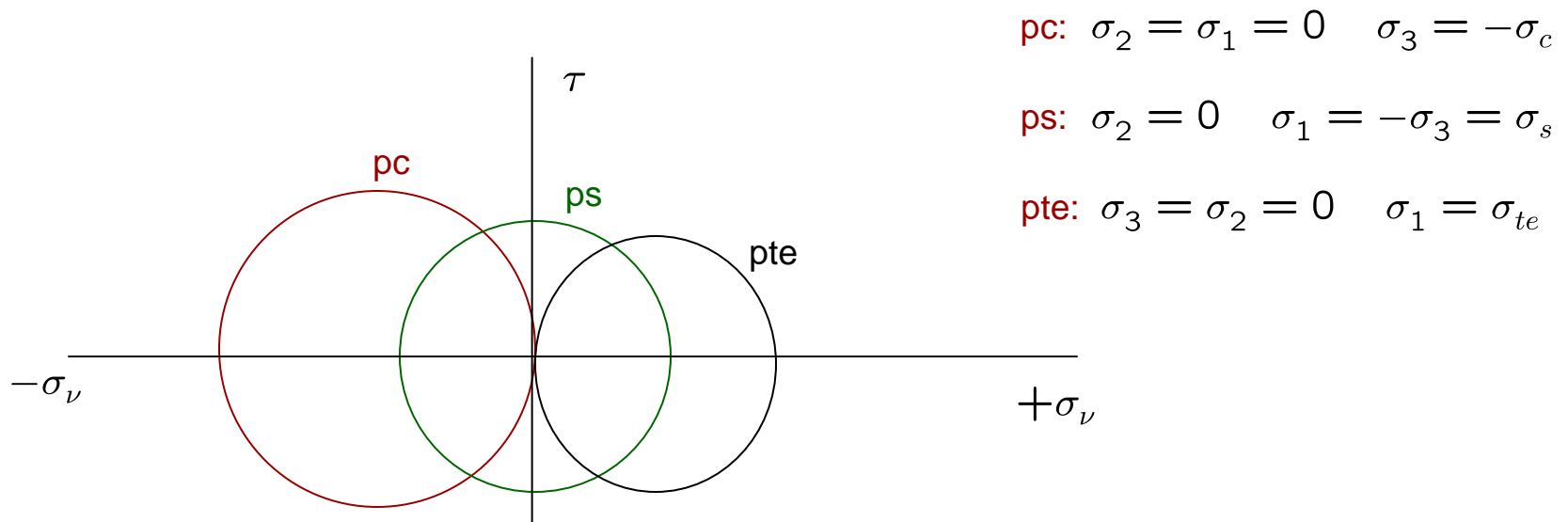
coefficient of internal friction

## Constitutive models: Failure Models

$$f(\sigma_{ij}) = 0$$

### Historical overview

Mohr 1882; 1900;    Mohr's principal circles -> Mohr's parabola as a hull for failure states



## Constitutive models: Failure Models

---

$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2}$$

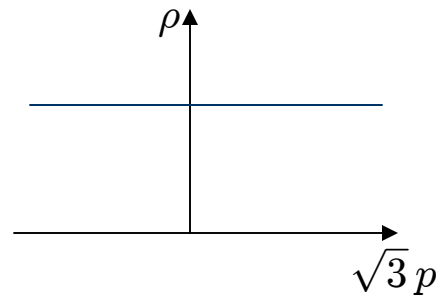
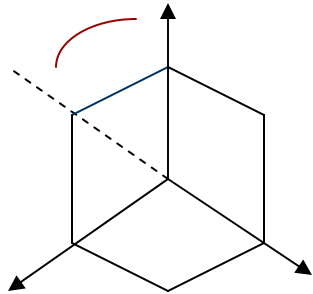
### One parameter failure models

Tresca (1868) shear stress criterion:

$$f(\rho, \Psi) = \rho \sin\left(\Psi + \frac{\pi}{3}\right) - \sqrt{2}k = 0 \quad \Psi \in [0, \pi/3]$$

for metals the hydrostatic pressure influence can be neglected

The material is at yield/failure when the maximum shear reaches a certain limit value  $k$  :



$$\sigma_1 - \sigma_3 = 2k$$

$$\sigma_1 = \max\{\sigma_i, i = 1, 2, 3\}$$

$$\sigma_3 = \min\{\sigma_i, i = 1, 2, 3\}$$

Reuß (1933):

$$f(I_1, J_2, J_3) = 4J_2^3 - 27J_3^2 - 36k^2J_2^2 + 96k^4J_2 - 64k^6 = 0$$

## Constitutive models: Failure Models

**Tresca (1868) shear stress criterion:**  $f(\rho, \Psi) = \rho \sin\left(\Psi + \frac{\pi}{3}\right) - \sqrt{2}k = 0$

Pure tension (te)

$$\Psi = 0 \rightarrow \rho_{te} = \frac{\sqrt{2}k}{\sin\frac{\pi}{3}} \rightarrow \rho_{te} = \frac{2\sqrt{2}k}{\sqrt{3}}$$

$$\rho_{te} = \sqrt{2J_2} = \sqrt{\left(\frac{4}{9}\sigma^2 + \frac{1}{9}\sigma^2 + \frac{1}{9}\sigma^2\right)} = \sqrt{\frac{2}{3}}\sigma$$



at failure  $\sigma = 2k$

Pure compression (c)

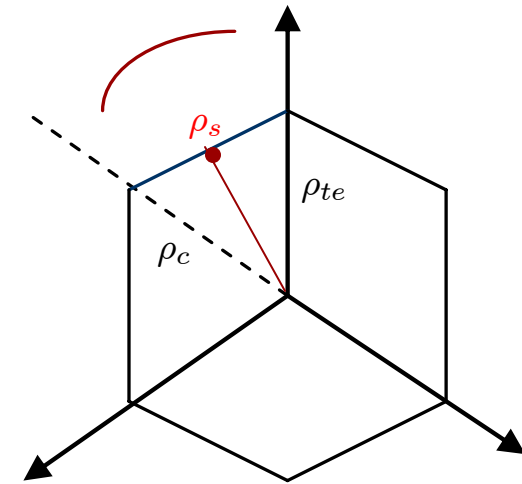
$$\Psi = \frac{\pi}{3} \rightarrow \rho_c = \frac{\sqrt{2}k}{\sin\frac{2\pi}{3}} \rightarrow \rho_c = \frac{2\sqrt{2}k}{\sqrt{3}}$$

Pure shear (s)

$$\Psi = \frac{\pi}{6} \rightarrow \rho_s = \frac{\sqrt{2}k}{\sin\frac{\pi}{2}} \rightarrow \rho_s = \sqrt{2}k$$

$$\rho_s = \sqrt{2J_2} = \sqrt{(\tau^2 + 0 + \tau^2)} = \sqrt{2}\tau$$

$$\sigma_1 - \sigma_3 = 2\tau$$



at pure shear failure

$$\tau = k$$

## Constitutive models: Failure Models

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$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2}$$

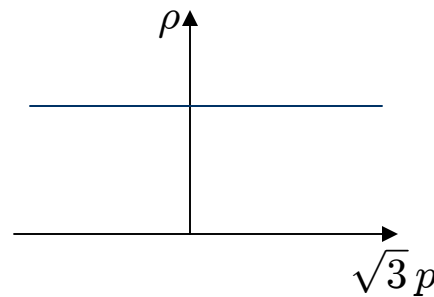
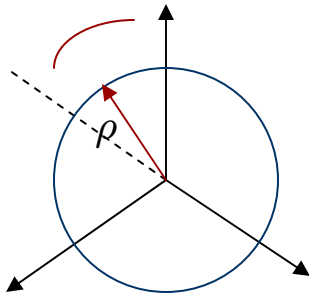
### One parameter failure models

**von Mises (1913) shear stress criterion:** the onset of yielding/failure does not depend on the first stress invariant (volumetric stress) -  $J_2$  plasticity

$$f(\rho) = \rho - \sqrt{2}k = 0$$

↓

magnitude of the shear stress at yielding in pure shear



The material yields when the distance of the corresponding stress point from the hydrostatic axis in the principal stress space reaches certain limit -> failure curve is a circle  
 since  $p$  has no influence -> meridians II to the hydrostatic axis  
 cylinder in principal stress space



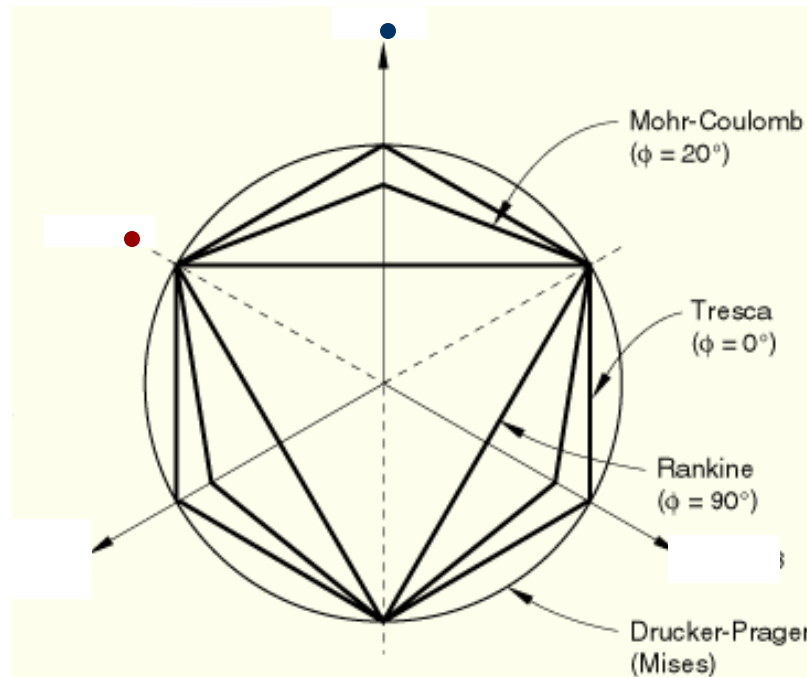
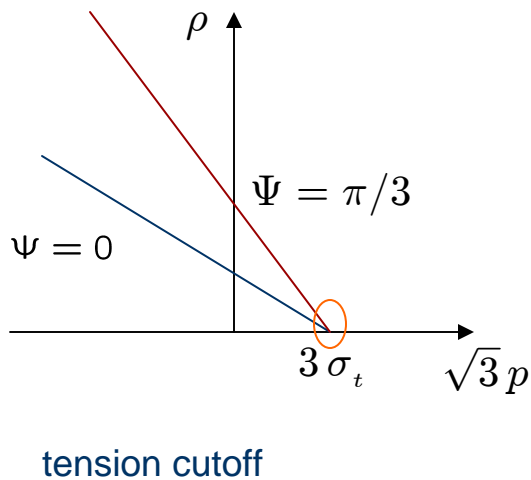
## Constitutive models: Failure Models

$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2} \quad \Psi \in [0, \pi/3]$$

**Rankine Criterion:** for modeling cracking of concrete (limited tensile capacity)

Yielding/failure starts when maximum principal stress reaches the tensile yield/failure stress -> it gives the triangular Rankine pyramid in the principal stress space

$$\sqrt{2} \rho \cos \Psi + \sqrt{3} p - \sqrt{3} \sigma_t = 0$$



## Constitutive models: Failure Models

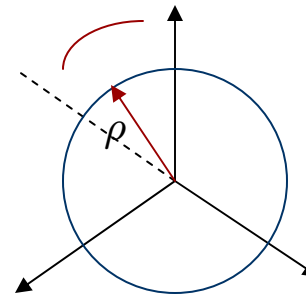
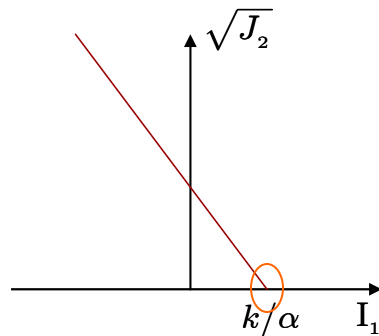
$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2}$$

### One parameter failure models

**Burzinski (1929) (B) – Drucker-Prager (1952) (D) model:** modelling failure for materials with internal friction: sand, soil, rock, concrete. Pressure sensitive failure (first invariant included in the model). Analogue to von Mises criterion but the value of the shear yield is adjusted according to the hydrostatic stress failure feature -> conical failure surface

$$f(I_1, J_2) = c_1 I_1 + c_2 I_1^2 + c_3 J_2 - 1 = 0 \quad (\text{B})$$

$$f(I_1, J_2) = \alpha I_1 + \sqrt{J_2} - k = 0 \quad (\text{D-P})$$



## Constitutive models: Failure Models

---

$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2}$$

### One parameter failure models

**Gurson (1977) model:** includes porosity (modeling powder compacted metals)

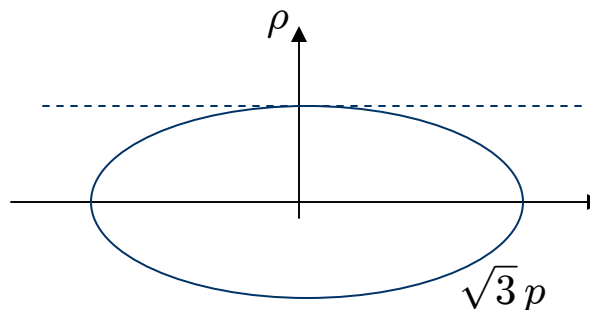
$$f(I_1, J_2, n) = \frac{3J_2}{k^2} + 2n \cosh \frac{I_1}{2k} - 1 - n^2 = 0$$

In the meridian plane is ellipsoid

$k$  - uniaxial yield/failure stress of the basic material (without pores)

$n$  - volume fraction of the voids (porosity)

Gurson model converges to von Mises model for  $n \rightarrow 0$



## Constitutive models: Failure Models

---

$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2}$$

### Two parameters failure models

sensitive to hydrostatic states of stress + assumption of geometrical similarity of the deviatoric cross sections of the failure surface

### Mohr- Coulomb failure model:

$$|\tau| = c - \sigma_\nu \tan \phi$$

Failure is assumed to occur when the shear stress  $\tau$  on any plane at a point in the material reaches a value that depends linearly upon the normal stress ( $\sigma_\nu$ ) in the same plane

$$f(p, J_2, \Psi) = p \sin \phi + \sqrt{J_2} \sin \left( \Psi + \frac{\pi}{3} \right) + \frac{\sqrt{J_2}}{\sqrt{3}} \cos \left( \Psi + \frac{\pi}{3} \right) \sin \phi - c \cos \phi = 0$$

$$\Psi \in [0, \pi/3]$$

## Constitutive models: Failure Models

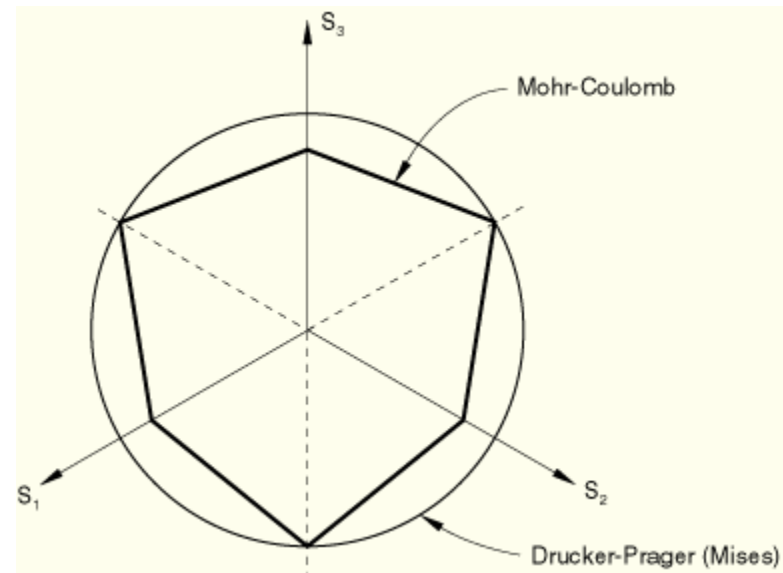
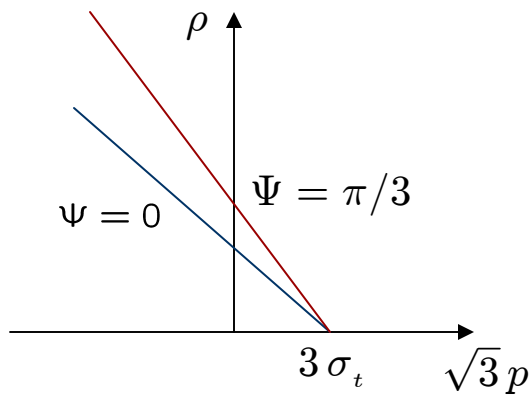
$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2} \quad \Psi \in [0, \pi/3]$$

$$f(\rho) = \rho - \sqrt{2}k = 0$$

von Mises

$$f(p, J_2, \Psi) = p \sin \phi + \sqrt{J_2} \sin\left(\Psi + \frac{\pi}{3}\right) + \frac{\sqrt{J_2}}{\sqrt{3}} \cos\left(\Psi + \frac{\pi}{3}\right) \sin \phi - c \cos \phi = 0$$

Mohr- Coulomb



## Constitutive models: Failure Models

$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2} \quad \Psi \in [0, \pi/3]$$

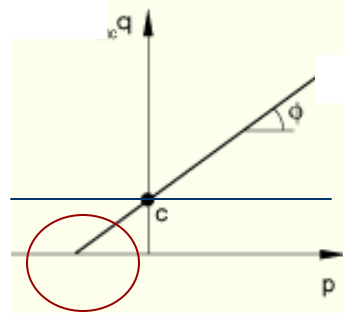
$$f(\rho, \Psi) = \rho \sin\left(\Psi + \frac{\pi}{3}\right) - \sqrt{2}k = 0 \quad \text{Tresca}$$

$$f(\rho) = \rho - \sqrt{2}k = 0 \quad \text{von Mises}$$

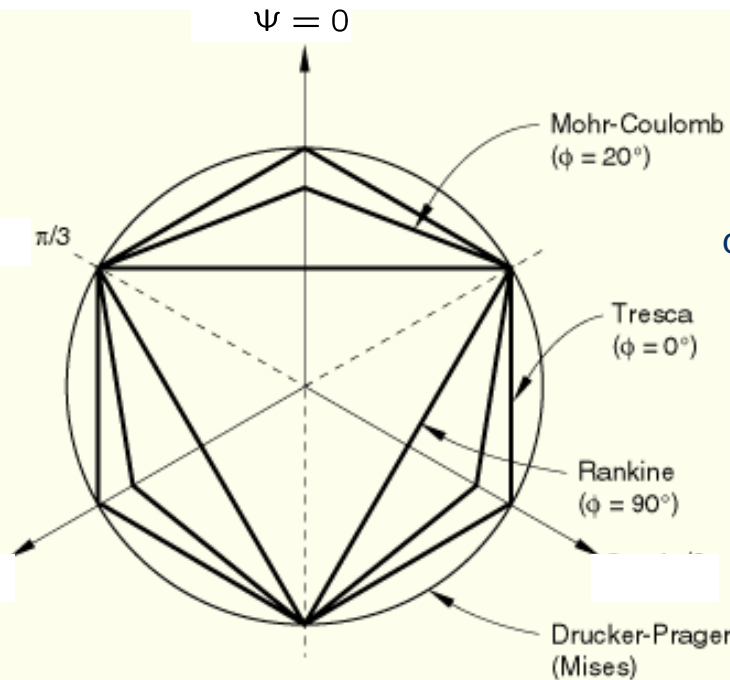
$$f(p, J_2, \Psi) = p \sin \phi + \sqrt{J_2} \sin\left(\Psi + \frac{\pi}{3}\right) + \frac{\sqrt{J_2}}{\sqrt{3}} \cos\left(\Psi + \frac{\pi}{3}\right) \sin \phi - c \cos \phi = 0$$

Mohr- Coulomb

meridian plane



compression positive!



deviatoric plane

## Constitutive models: Failure Models

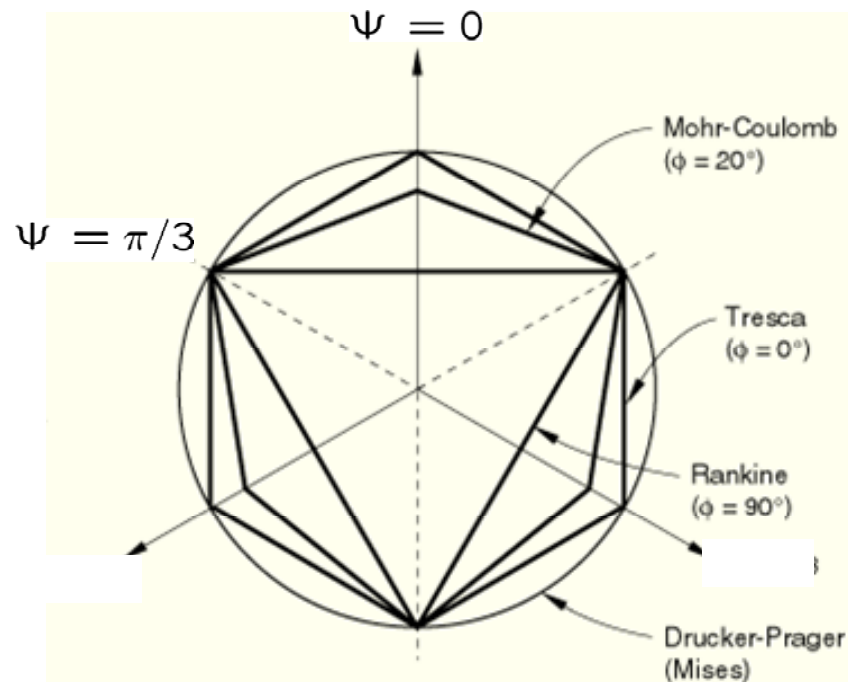
$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2} \quad \Psi \in [0, \pi/3]$$

$$f(\rho, \Psi) = \rho \sin\left(\Psi + \frac{\pi}{3}\right) - \sqrt{2}k = 0 \quad \text{Tresca}$$

$$f(\rho) = \rho - \sqrt{2}k = 0 \quad \text{von Mises}$$

$$f(p, J_2, \Psi) = p \sin \phi + \sqrt{J_2} \sin\left(\Psi + \frac{\pi}{3}\right) + \frac{\sqrt{J_2}}{\sqrt{3}} \cos\left(\Psi + \frac{\pi}{3}\right) \sin \phi - c \cos \phi = 0$$

Mohr- Coulomb



## Constitutive models: Failure Models

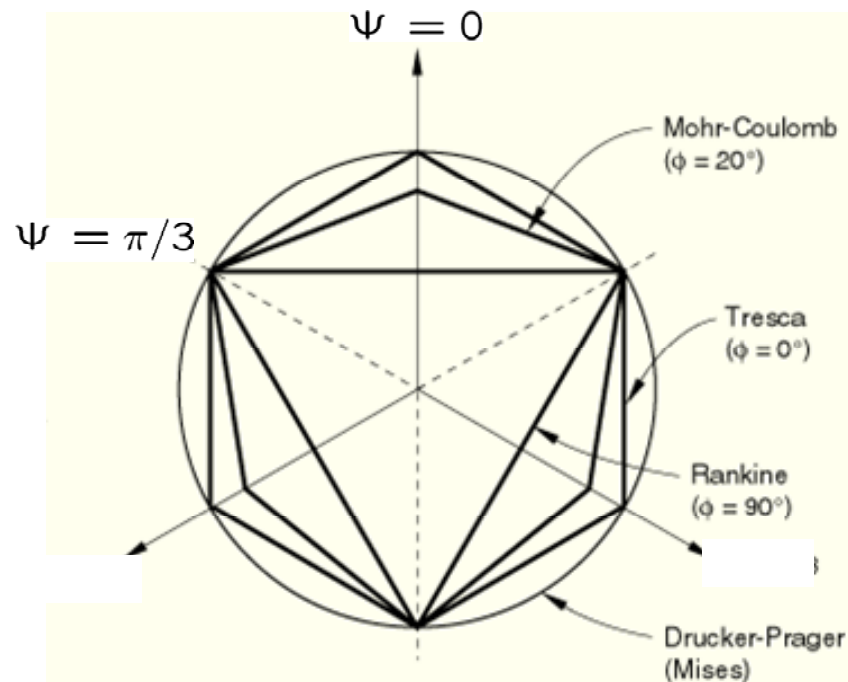
$$f(\sqrt{3}p, \rho, \Psi) = 0, \quad \rho = \sqrt{2J_2} \quad \Psi \in [0, \pi/3]$$

$$f(\rho, \Psi) = \rho \sin\left(\Psi + \frac{\pi}{3}\right) - \sqrt{2}k = 0 \quad \text{Tresca}$$

$$f(\rho) = \rho - \sqrt{2}k = 0 \quad \text{von Mises}$$

$$f(p, J_2, \Psi) = p \sin \phi + \sqrt{J_2} \sin\left(\Psi + \frac{\pi}{3}\right) + \frac{\sqrt{J_2}}{\sqrt{3}} \cos\left(\Psi + \frac{\pi}{3}\right) \sin \phi - c \cos \phi = 0$$

Mohr- Coulomb





## Constitutive models: Elasto-Plastic Models

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**Plasticity** is the property of the solid body to deform under applied external force and to possess permanent or temporal residual deformation after the applied load is removed.

Main feature of plasticity:

$$\sigma \sim \varepsilon$$

is not uniquely determined by the current state.

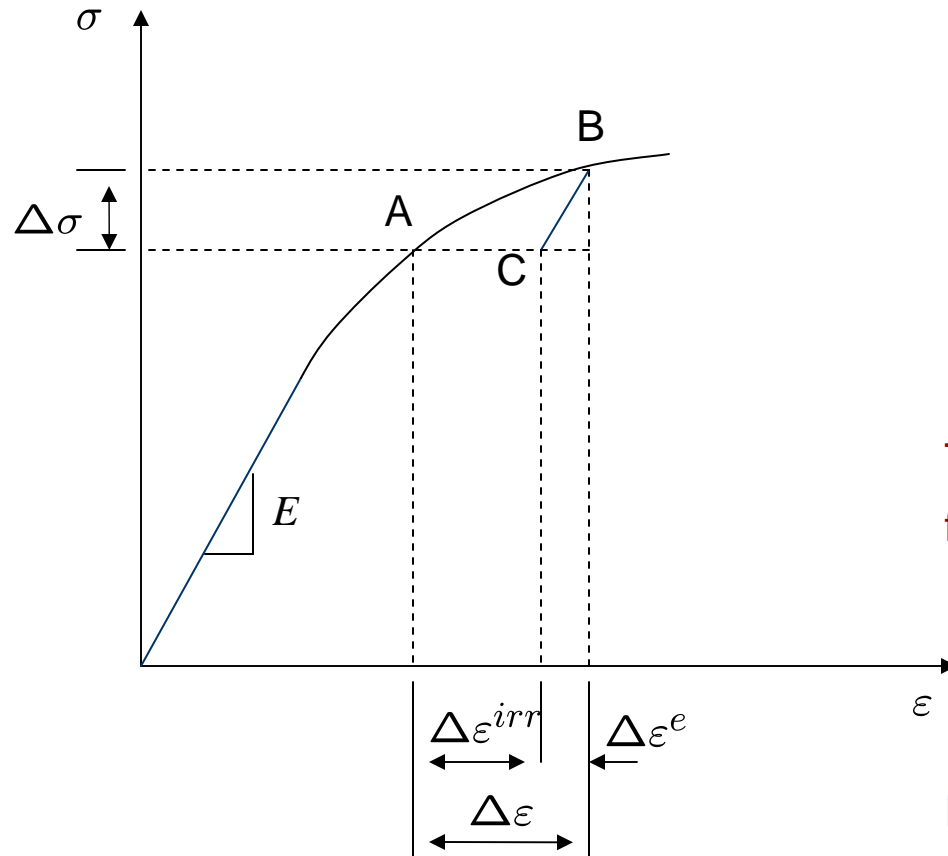
**Elastic state** of a solid body is a state at which an independent of time uniquely determined relationship between stresses and strains exists for any given temperature.

**Plastic state** of a solid body is a state at which for a given temperature the relationship between stresses and strains at each moment of time becomes uniquely determined if at least one (or all) preceding stress-strain state and the corresponding to it temperature are known.

Otherwise  $\sigma \sim \varepsilon$  is not determined.

## Constitutive models: Elasto-Plastic Models

1D  $\longleftrightarrow$  3D



uniaxial test

- Reversible elastic deformation
- Irreversible, inelastic deformation

Term plastic deformation will be used for inelastic time – independent strain

Inelastic deformation may be:  
– creep (time dependent);  
– viscoplastic (rate dependent)